

Optimising Functional Programs with Equality Saturation

Thomas KÆHLER

Michel STEUWER



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Term Rewriting

Which rewrite rule should be applied when, and where?

Desired optimisation:

$$(a * 2)/2 \longrightarrow a * (2/2) \longrightarrow a * 1 \longrightarrow a$$

Wrong turn:

$$(a * 2)/2 \longrightarrow (a \ll 1)/2$$

Infinite loop:

$$(a * 2)/2 \longrightarrow (2 * a)/2 \longrightarrow (a * 2)/2 \longrightarrow \dots$$

Equality Saturation

Which rewrite rule should be applied when, and where?

Explore all possibilities

[Tate et al. 2009 “Equality saturation: a new approach to optimization”]

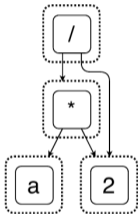
[Willsey et al. 2021 “egg: fast and extensible equality saturation”]

- + No need to decide which rewrite to apply next,
Decide which program variant you want in the end.
- Need to efficiently represent and rewrite many programs.

Equality Saturation

E-Graphs

$$(a * 2) / 2 \longrightarrow^* a$$

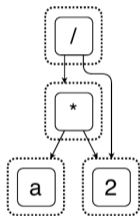


$$(a * 2) / 2$$

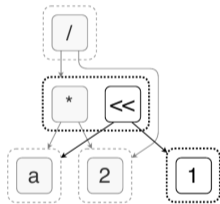
Equality Saturation

E-Graphs

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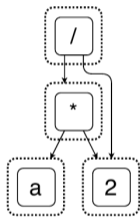


$$x * 2 \longrightarrow x \ll 1$$

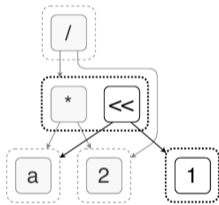
Equality Saturation

E-Graphs

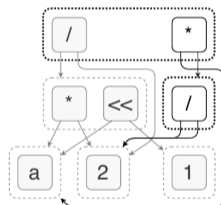
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$$(a * 2)/2$$



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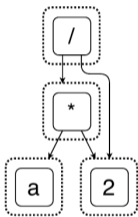


$$(x * y)/z \longrightarrow x * (y/z)$$

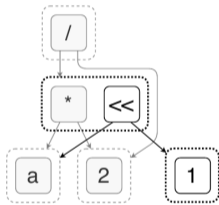
Equality Saturation

E-Graphs

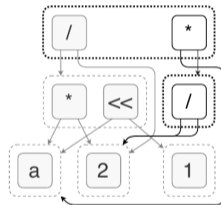
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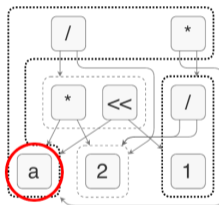
$$(a * 2) / 2$$



$$x * 2 \longrightarrow x \ll 1$$



$$(x * y) / z \longrightarrow x * (y / z)$$



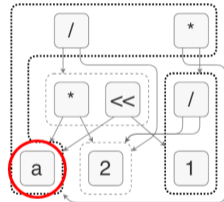
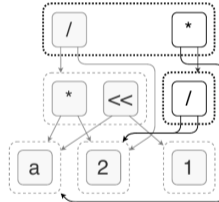
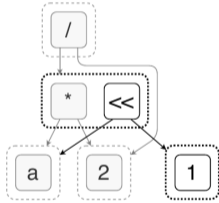
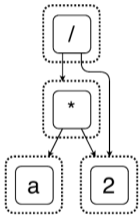
$$x / x \longrightarrow 1$$

$$x * 1 \longrightarrow x$$

Equality Saturation

E-Graphs

$$(a * 2) / 2 \longrightarrow^* a$$



How does it work for functional programs?

Equality Saturation for Functional Programs?

Rewriting RISE programs (typed lambda calculus with computational patterns):

$(\lambda x. b)e \longrightarrow b[e/x]$ (β -reduction)

$\lambda x. f x \longrightarrow f$ if x not free in f (η -reduction)

$map\ f\ (map\ g\ arg) \longrightarrow map\ (\lambda x. f\ (g\ x))\ arg$ (map-fusion)

$map\ (\lambda x. f\ gx) \longrightarrow \lambda y. map\ f\ (map\ (\lambda x. gx)\ y)$ if x not free in f (map-fission)

How can we implement **substitution**, **predicates** and **name bindings**?

Substitution

$$(\lambda x. b)e \longrightarrow b[e/x] \quad (\beta\text{-reduction})$$

- ▶ Small-step explicit substitution: simple but inefficient
 - ▶ overloads the e-graph with intermediate steps
- ▶ Big-step substitution over the e-graph: open challenge
- ▶ Extraction-based substitution: efficient but approximated
 1. extract terms from the e-classes b and e
 2. perform a standard term substitution
 3. insert the result back into the e-graph

Substitution

$$(\lambda x. b)e \longrightarrow b[e/x] \quad (\beta\text{-reduction})$$

- ▶ Small-step explicit substitution: simple but inefficient
 - ▶ (1) is not found: out of memory after multiple seconds ✗
- ▶ Extraction-based substitution: efficient but approximated
 - ▶ (1) is found in milliseconds ✓

$$\mathit{map} (\lambda x. f_4 (f_3 (f_2 (f_1 x)))) \longrightarrow^* \lambda y. \mathit{map} (\lambda x. f_4 (f_3 x)) (\mathit{map} (\lambda x. f_2 (f_1 x)) y) \quad (1)$$

Predicates

$\lambda x. f x \longrightarrow f$ if x not free in f (η -reduction)

- ▶ if $\forall t \in f. x$ not free in t : ignores valid terms
- ▶ if $\exists t \in f. x$ not free in t : accepts invalid terms
- ▶ filter f into $f_2 = \{t \mid t \in f, x \text{ not free in } t\}$: open challenge

Name Bindings

$$\text{map } f(\text{map } g \text{ arg}) \longrightarrow \text{map } (\lambda x. f(g x)) \text{ arg} \quad (\text{map-fusion})$$

- ▶ Fresh name on every rewrite: inefficient
 - ▶ equality modulo alpha renaming is not built-in
 - ▶ generates more and more alpha-equivalent programs
- ▶ DeBruijn indices: significant improvement
 - ▶ but no equality modulo alpha renaming for sub-terms
- ▶ To investigate: build alpha-equivalence into the e-graph
[Maziarz et al. 2021 “Hashing modulo alpha-equivalence”]

Name Bindings

$$\text{map } f(\text{map } g \text{ arg}) \longrightarrow \text{map } (\lambda x. f(g x)) \text{ arg} \quad (\text{map-fusion})$$

- ▶ Fresh name on every rewrite: inefficient
 - ▶ cannot find optimised 2D convolution¹: out of memory after multiple minutes ✗
- ▶ DeBruijn indices: significant improvement
 - ▶ finds optimised 2D convolution¹ in 2s ✓

¹sequence of 13 rewrite rules, not counting α and β reductions

Avoiding Name Bindings using Combinators

$$\begin{aligned} f(g\ x) &\longrightarrow (f \circ g)\ x && (\circ\text{-intro}) \\ \text{map } f \circ \text{map } g &\longrightarrow \text{map } (f \circ g) && (\text{map-fusion}_2) \\ \text{map } (f \circ g) &\longrightarrow \text{map } f \circ \text{map } g && (\text{map-fission}_2) \end{aligned}$$

instead of

$$\begin{aligned} \text{map } f(\text{map } g\ \text{arg}) &\longrightarrow \text{map } (\lambda x. f(g(x)))\ \text{arg} && (\text{map-fusion}) \\ \text{map } (\lambda x. f\ gx) &\longrightarrow \lambda y. \text{map } f(\text{map } (\lambda x. gx))\ y && \text{if } x \text{ not free in } f \quad (\text{map-fission}) \end{aligned}$$

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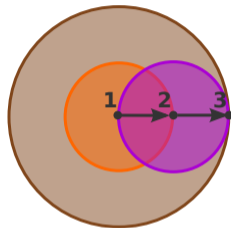
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enables re-ordering 4D and tiling 2D loops in 30s ✓ *(with additional tricks)*

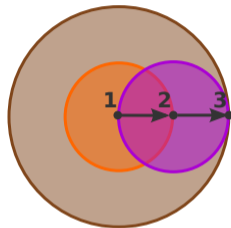
Future Work

- ▶ We still cannot optimise large real-world RISE programs
matrix multiplication, corner detection, ..
- ▶ We want to explore many possibilities, but not all of them
- ▶ I am interested in focusing the search by:
 - ▶ deleting or filtering programs
 - ▶ enforcing normal forms
 - ▶ controlling optimisations using rewriting strategies
 - ▶ leveraging heuristics to prioritize promising directions



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✉ thomas.koehler@thok.eu

🌐 thok.eu

Thanks!

🌐 rise-lang.org
🌐 elevate-lang.org

Adding Types

Consider $(\lambda x. x) (0 : int)$ and $(\lambda x. x) (0.0 : float)$

- ▶ Keeping types polymorphic enables more sharing:

$$\lambda x. x : \forall t. t \rightarrow t$$

- ▶ Instantiating types enables more precise type-based rewriting:

$$\lambda x. x : int \rightarrow int$$

$$\lambda x. x : float \rightarrow float$$

Trade-off between amount of sharing and amount of information