

OptiTrust: an Interactive Optimization Framework

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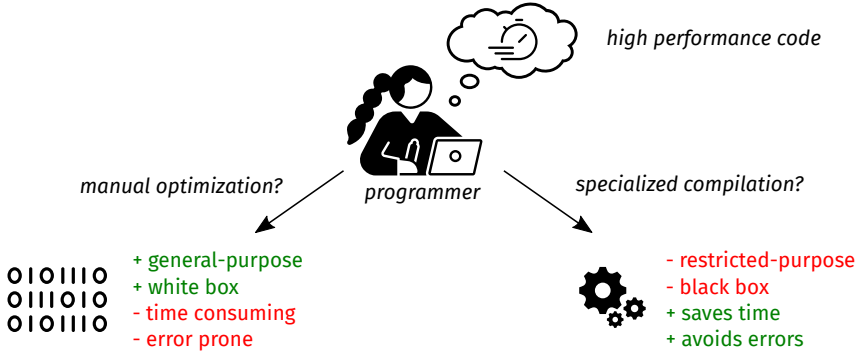
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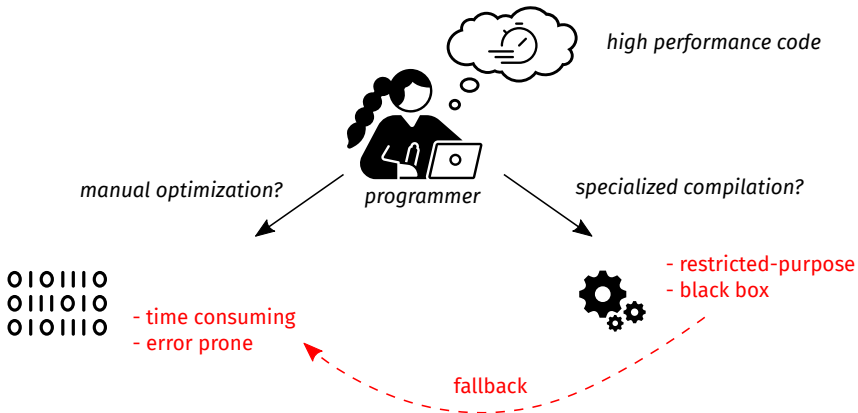


ARRAY Workshop — Orlando, June 2023

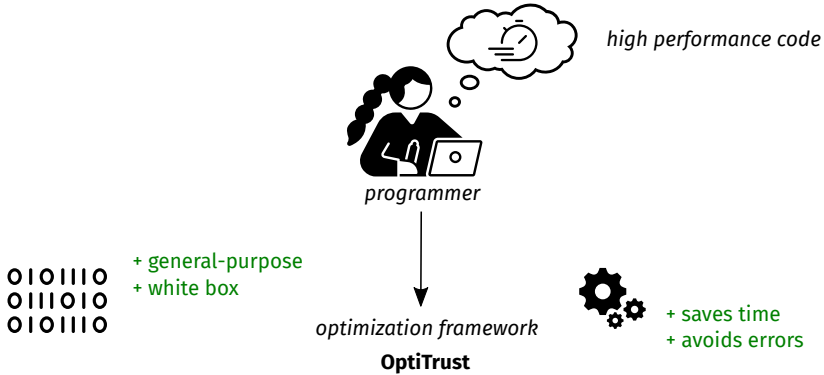
Why OptiTrust?



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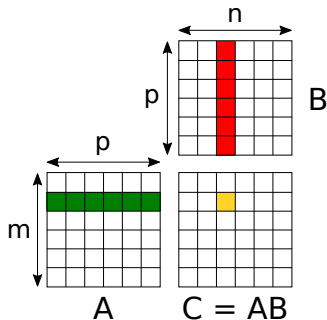
Example: Optimizing Matrix Multiplication

A standard benchmark to:

- ▶ showcase OptiTrust user experience
- ▶ compare to user-guided specialized compilers (*TVM*)

Unoptimized Matrix Multiplication

```
for (int i = 0; i < m; i++) {  
  for (int j = 0; j < n; j++) {  
    float sum = 0.0f;  
    for (int k = 0; k < p; k++) {  
      sum += A[i][k] * B[k][j];  
    }  
    C[i][j] = sum;  
  }  
}
```



Optimization by Hand

```
float* pB = (float*) malloc(sizeof(float)[32][256][4][32]));
#pragma omp parallel for
for (int bj = 0; bj < 32; bj++) for (int bk = 0; bk < 256; bk++) {
    for (int k = 0; k < 4; k++) for (int j = 0; j < 32; j++) {
        pB[32768 * bj + 128 * bk + 32 * k + j] =
            B[1024 * (4 * bk + k) + 32 * bj + j]; }
#pragma omp parallel for
for (int bi = 0; bi < 32; bi++) for (int bj = 0; bj < 32; bj++) {
    float* sum = (float*) malloc(sizeof(float)[32][32]));
    for (int i = 0; i < 32; i++) for (int j = 0; j < 32; j++) {
        sum[32 * i + j] = 0.; }
    for (int bk = 0; bk < 256; bk++) for (int i = 0; i < 32; i++) {
        float s[32];
        memcpy(s, &sum[32 * i], sizeof(float)[32]);
#pragma omp simd
        for (int j = 0; j < 32; j++) { // k = 0
            s[j] += A[1024 * (32 * bi + i) + 4 * bk + 0] *
                pB[32768 * bj + 128 * bk + 32 * 0 + j]; }
        // [ ... ] k = 1, 2, 3
        memcpy(&sum[32 * i], s, sizeof(float)[32]); }
    for (int i = 0; i < 32; i++) for (int j = 0; j < 32; j++) {
        C[1024 * (32*bi + i) + 32*bj + j] = sum[32*i + j]; }
// [ ... ] free instructions
```

- Standard optimizations:
 - improve data locality
transform loops, change data layout
 - add parallelism
vectorization, multi-threading
- 150× faster
Intel i7-8665U, 4 cores, AVX2
- Time consuming
- Error prone
- 5× more lines of code

Optimization with TVM

TVM Algorithm = what to compute

```
k = tvm.reduce_axis((0, P))
A = tvm.placeholder((M, P))
B = tvm.placeholder((P, N))

C = tvm.compute((M, N),
    lambda i, j:
        sum(A[i, k] * B[k, j], axis=k))
```

Rewritten Algorithm

```
pB = tvm.compute((N / 32, P, 32),
    lambda bj, k, j:
        B[k, bj * 32 + j])

C = tvm.te.compute((M, N),
    lambda i, j:
        sum(A[i, k] *
            pB[j // 32, k, j % 32],
            axis=k))
```

TVM Schedule = how to compute

```
CC = s.cache_write(C, "global")
bi, bj, i, j = s[C].tile(
    C.op.axis[0], C.op.axis[1], 32, 32)
s[CC].compute_at(s[C], bj)
i2, j2 = s[CC].op.axis
(kaxis,) = s[CC].op.reduce_axis
bk, k = s[CC].split(kaxis, factor=4)
s[CC].reorder(bk, i2, k, j2)
s[CC].vectorize(j2)
s[CC].unroll(k)
s[C].parallel(bi)
bj3, _, j3 = s[pB].op.axis
s[pB].vectorize(j3)
s[pB].parallel(bj3)
```

- **Convenient** *quickly try many schedules*
- **Restricted** *algorithm DSL + schedule API*
- **Black box** *implicit heuristics + unfamiliar IR*

Optimization with OptiTrust

OptiTrust Transformation Script

```
let tile (loop_id, size) = Loop.tile (int size) ~index:("b" ^ loop_id) ~bound:TileDivides [cFor loop_id] in
!! List.iter tile [("i", 32); ("j", 32); ("k", 4)];
!! Loop.reorder_at ~order:["bi"; "bj"; "bk"; "i"; "k"; "j"] [cPlusEq [cVar "sum"]];
!! Loop.hoist_expr ~dest:[tBefore; cFor "bi"] "pB" ~indep:["bi"; "i"] [cArrayRead "B"];
!! Function.inline_def [cFunDef "mm"];
!! Matrix.stack_copy ~var:"sum" ~copy_var:"s" ~copy_dims:1 [cFor ~body:[cPlusEq [cVar "sum"]] "k"];
!! Matrix.elim_mops [];
!! Loop.unroll [cFor ~body:[cPlusEq [cVar "s"]] "k"];
!! Omp.simd [nbMulti; cFor ~body:[cPlusEq [cVar "s"]] "j"];
!! Omp.parallel_for [nbMulti; cFunBody "mm1024"; cStrict; cFor ""];
```

- ▶ transformation script = sequence of transformation steps (!!)
- ▶ **transformation** = function modifying the current program
- ▶ *target* = data structure describing where to apply transformations
- ▶ scripts are written in OCaml: **let**, **List.iter**, ..

Interacting with OptiTrust

<pre>void mm(float* C, float* A, float* B, int m, int n, int p) { - for (int i = 0; i < m; i++) { - for (int j = 0; j < n; j++) { float sum = 0.f; - for (int k = 0; k < p; k++) { - sum += A[i][k] * B[k][j]; - } - C[i][j] = sum; - } - } }</pre>	<pre>void mm(float* C, float* A, float* B, int m, int n, int p) { + for (int bi = 0; bi < exact_div(m, 32); bi++) { + for (int i = 0; i < 32; i++) { + for (int bj = 0; bj < exact_div(n, 32); bj++) { + for (int j = 0; j < 32; j++) { + float sum = 0.f; + for (int bk = 0; bk < exact_div(p, 4); bk++) { + for (int k = 0; k < 4; k++) { + sum += A[bi * 32 + i][bk * 4 + k] * B[bk * 4 + k][t + } + } + C[bi * 32 + i][bj * 32 + j] = sum; + } + } + } + } }</pre>
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- ▶ pressing "F6" on a transformation step opens the corresponding diff. *first step above*
- ▶ pressing "Maj+F5" opens a trace of all transformations. *next slide*

```
!!! Loop.hoist_expr -dest:[tBefore; cFor "bi"] "pB" -indep:["bi"; "i"] [cArrayRead "B"];
```

<div><div><div>• Variable.bind</div><div>• Loop.hoist_alloc</div><div>◦ Variable.init_detach</div><div>◦ Matrix.intro_malloc0</div><div>◦ Loop.hoist</div><div>◦ Loop.hoist</div><div>◦ Loop.move_out</div><div>◦ Instr.move</div><div>◦ Loop.hoist</div><div>◦ Loop.hoist</div><div>◦ Loop.move_out</div><div>◦ Instr.move</div><div>◦ Variable.to_const</div><div>◦ Variable.inline</div><div>◦ Variable.to_const</div><div>◦ Variable.inline</div><div>◦ Variable.to_const</div><div>◦ Variable.inline</div><div>◦ Variable.to_const</div><div>◦ Variable.inline</div><div>◦ Variable.rename</div><div>• Loop.hoist_instr</div><div>◦ Loop.fission</div><div>◦ Loop.fission</div><div>◦ Loop.move_out</div><div>◦ Loop.fission</div><div>◦ Instr.move</div><div>◦ Loop.fission</div><div>◦ Loop.move_out</div></div></div>	<pre>1 #include "../include/optitrust.h" 2 #include "matmul.h" 3 #include "omp.h" 4 // NOTE: using pretty matrix notation 5 6 void mm(float* C, float* A, float* B, int m, int n, int p) { 7 8 9 10 11 12 13 14 15 16 17 18 19 for (int bi = 0; bi < exact_div(m, 32); bi++) { 20 for (int bj = 0; bj < exact_div(n, 32); bj++) { 21 float* sum = (float*)malloc(sizeof(float[32][32])); 22 for (int i = 0; i < 32; i++) { 23 for (int j = 0; j < 32; j++) { 24 sum[i][j] = 0.f; 25 } 26 } 27 for (int bk = 0; bk < exact_div(p, 4); bk++) { 28 for (int i = 0; i < 32; i++) { 29 for (int k = 0; k < 4; k++) { 30 for (int j = 0; j < 32; j++) { 31 - sum[i][j] += 32 - A[bi * 32 + i][bk * 4 + k] * B[bk * 4 + k][bj * 32 + j]; 33 } 34 } 35 } 36 } 37 for (int i = 0; i < 32; i++) { 38 for (int j = 0; j < 32; j++) { 39 C[bi * 32 + i][bj * 32 + j] = sum[i][j]; 40 } 41 } 42 free(sum); 43 } 44 }</pre>	<pre>1 #include "../include/optitrust.h" 2 #include "matmul.h" 3 #include "omp.h" 4 // NOTE: using pretty matrix notation 5 6 void mm(float* C, float* A, float* B, int m, int n, int p) { 7 + float* pB = 8 + (float*)malloc(sizeof(float[exact_div(n, 32)][exact_div(p, 4)][4][32])); 9 + for (int bj = 0; bj < exact_div(n, 32); bj++) { 10 + for (int bk = 0; bk < exact_div(p, 4); bk++) { 11 + for (int k = 0; k < 4; k++) { 12 + for (int j = 0; j < 32; j++) { 13 + pB[bj][bk][k][j] = B[bk * 4 + k][bj * 32 + j]; 14 + } 15 + } 16 + } 17 + } 18 for (int bi = 0; bi < exact_div(m, 32); bi++) { 19 for (int bj = 0; bj < exact_div(n, 32); bj++) { 20 float* sum = (float*)malloc(sizeof(float[32][32])); 21 for (int i = 0; i < 32; i++) { 22 for (int j = 0; j < 32; j++) { 23 sum[i][j] = 0.f; 24 } 25 } 26 for (int bk = 0; bk < exact_div(p, 4); bk++) { 27 for (int i = 0; i < 32; i++) { 28 for (int k = 0; k < 4; k++) { 29 for (int j = 0; j < 32; j++) { 30 + sum[i][j] += A[bi * 32 + i][bk * 4 + k] * pB[bj][bk][k][j]; 31 } 32 } 33 } 34 } 35 for (int i = 0; i < 32; i++) { 36 for (int j = 0; j < 32; j++) { 37 C[bi * 32 + i][bj * 32 + j] = sum[i][j]; 38 } 39 } 40 free(sum); 41 } 42 }</pre>
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<ul style="list-style-type: none"> Variable.bind Loop.hoist_alloc <ul style="list-style-type: none"> Variable.init_detach Matrix.intro_malloc0 Loop.hoist Loop.hoist Loop.move_out Instr.move Loop.hoist Loop.hoist Loop.move_out Instr.move Variable.to_const Variable.inline Variable.to_const Variable.inline Variable.to_const Variable.inline Variable.to_const Variable.inline Variable.rename Loop.hoist_instr <ul style="list-style-type: none"> Loop.fission Loop.fission Loop.move_out Loop.fission Instr.move Loop.fission Loop.move_out 	<pre> 9 float* sum = (float*)malloc(sizeof(float)[32][32]); 10 for (int i = 0; i < 32; i++) { 11 for (int j = 0; j < 32; j++) { 12 sum[i][j] = 0.f; 13 } 14 } 15 for (int bk = 0; bk < exact_div(p, 4); bk++) { 16 for (int i = 0; i < 32; i++) { 17 for (int k = 0; k < 4; k++) { 18 for (int j = 0; j < 32; j++) { 19 - sum[i][j] += 20 - A[bi * 32 + i][bk * 4 + k] * B[bk * 4 + k][bj * 32 + j]; 21 } 22 } 23 } 24 } 25 for (int i = 0; i < 32; i++) { 26 for (int j = 0; j < 32; j++) { 27 C[bi * 32 + i][bj * 32 + j] = sum[i][j]; 28 } 29 } 30 free(sum); </pre>	<pre> 9 float* sum = (float*)malloc(sizeof(float)[32][32]); 10 for (int i = 0; i < 32; i++) { 11 for (int j = 0; j < 32; j++) { 12 sum[i][j] = 0.f; 13 } 14 } 15 for (int bk = 0; bk < exact_div(p, 4); bk++) { 16 for (int i = 0; i < 32; i++) { 17 for (int k = 0; k < 4; k++) { 18 for (int j = 0; j < 32; j++) { 19 + float pB = B[bk * 4 + k][bj * 32 + j]; 20 + sum[i][j] += A[bi * 32 + i][bk * 4 + k] * pB; 21 } 22 } 23 } 24 } 25 for (int i = 0; i < 32; i++) { 26 for (int j = 0; j < 32; j++) { 27 C[bi * 32 + i][bj * 32 + j] = sum[i][j]; 28 } 29 } 30 free(sum); </pre>
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Transformations are Composed into Abstractions

9 script steps result in >60 basic steps of >20 basic transformations:

- ▶ **Arith**: simpl
- ▶ **Sequence**: delete, elim
- ▶ **Function**: inline
- ▶ **Variable**: inline, bind, init_detach
- ▶ **Instr**: move
- ▶ **Array**: inline_constant
- ▶ **Matrix**: intro_malloc0, copy_to_stack, elim_mindex
- ▶ **Loop**: fission, swap, hoist, move_out, tile, unroll
- ▶ **Omp**: parallel_for, simd
- ▶ ...

Example Recap

OptiTrust Transformation Script

```
let tile (loop_id, size) = Loop.tile (* ... *) [cFor loop_id] in
!! List.iter tile [("i", 32); ("j", 32); ("k", 4)];
!! Loop.reorder_at -order:["bi"; "bj"; "bk"; "i"; "k"; "j"]
   [cPlusEq [cVar "sum"]];
!! Loop.hoist_expr -dest:[tBefore; cFor "bi"] "pB"
   -indep:["bi"; "i"] [cArrayRead "B"];
!! Function.inline_def [cFunDef "mm"];
!! Matrix.stack_copy -var:"sum" -copy_var:"s" -copy_dims:1
   [cFor -body:[cPlusEq [cVar "sum"]] "k"];
!! Matrix.elim_mops [];
!! Loop.unroll [cFor -body:[cPlusEq [cVar "s"]] "k"];
!! Omp.simd [nbMulti; cFor -body:[cPlusEq [cVar "s"]] "j"];
!! Omp.parallel_for [nbMulti; cFunBody ""; cStrict; cFor ""];
```

TVM Schedule

```
CC = s.cache_write(C, "global")
bi, bj, i, j = s[C].tile(
    C.op.axis[0], C.op.axis[1], 32, 32)
s[CC].compute_at(s[C], bj)
i2, j2 = s[CC].op.axis
(kaxis,) = s[CC].op.reduce_axis
bk, k = s[CC].split(kaxis, factor=4)
s[CC].reorder(bk, i2, k, j2)
s[CC].vectorize(j2)
s[CC].unroll(k)
s[C].parallel(bi)
bj3, _, j3 = s[pB].op.axis
s[pB].vectorize(j3)
s[pB].parallel(bj3)
```

- ▶ achieves the same performance as the TVM schedule
- ▶ transforms C code rather than specialized languages / IRs
- ▶ is interactive, providing diffs and traces of familiar C code
- ▶ is reasonably concise compared to a specialized API

general-purpose

white box

still saves time

Ongoing Work: Justifying Transformation Correctness

- Memory resources are annotated in a subset of Separation Logic:

Initial Matrix Multiplication Annotations

```
void mm(float* C, float* A, float* B, int m, int n, int p) {  
    __modifies("C => Matrix(m, n)");  
    __reads("A => Matrix(m, p); B => Matrix(p, n)");  
    // [...]  
}
```

- From few annotations, resources are computed at every code location:

Computed Resources for Accumulation Instruction

```
__reads("A => Matrix(m, p); B => Matrix(p, n)");  
__modifies("sum => Cell");  
sum += A[i][k] * B[k][j];
```

Ongoing Work: Justifying Transformation Correctness

Transformations can:

- Leverage resources to justify their correctness:

avoids errors

`Omp.parallel_for` is correct when each iteration has separate writes.

```
#pragma omp parallel for
for (int bi = 0; bi < exact_div(m, 32); bi++) {
    __only_this_iteration_modifies("C => MatrixTile((bi, 32), (0, n))");
```

- Transform annotations to change view on resources:

```
Omp.parallel_for ~modifies:"C => MatrixTile((bi, 32), (0, n))"
__ghost("Matrix.tile_dim(C, (0, 32), (0, n))");
// ^ consumes 'C => Matrix(m, n)', produces C tiles
for (int bi = 0; bi < exact_div(m, 32); bi++) {
    __only_this_iteration_modifies("C => MatrixTile((bi, 32), (0, n))");
```

Conclusion

- ▶ OptiTrust is an interactive framework for optimizing general-purpose C code
- ▶ 3 existing case studies:
 - ▶ Matrix Multiplication : same performance as TVM in 9 script steps
 - ▶ Harris Corner Detection : same performance as Halide in 11 script steps ([Stencil.](#))
 - ▶ Particle-In-Cell : beyond specialized compilers in 140 script steps
- ▶ Questions for the ARRAY community:
 - ▶ Gradual transition between high-level array programming, and interactive optimization?
 - ▶ Implement array compilation techniques as transformations that can be reused and applied to hybrid code?

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Backup Slides

Matrix Multiplication Performance

- ▶ Intel(R) Core(TM) i7-8665U CPU, AVX2 (8 floats), 4 cores (8 hyperthreads)
- ▶ Relative speedup on 1024^3 input:

version	single-thread	multi-thread
unoptimized	1×	1×
optimized	46×	150×
TVM	46×	150×
numpy (Intel MKL) ¹	71×	183×

Both codes have 90th percentile runtime of 9.4ms over 200 benchmark runs, corresponding to a speedup of 150× compared to the 90th percentile of the naive code.

¹uses assembly code, explicit vectorization, custom thread library

Harris Script

OptiTrust transformation script for Harris corner detection

```
let fuse (ops, overlaps, outputs) =  
  Stencil.fusion_targets -nest_of:2 -outputs -overlaps [ctx; any cFun ops] in  
let overlaps_2x2 vars = List.map (fun i -> i, [int 2; int 2]) vars in  
!! List.iter fuse  
  ["grayscale"], [], ["gray"];  
  ["sobelX"; "sobelY"], [], ["ix"; "iy"];  
  ["mul"; "sum3x3"; "coarsity"], overlaps_2x2 ["ixx"; "ixy"; "iyy"], ["out"]];  
!! Stencil.fusion_targets_tile [int 32] -outputs:["out"]  
  -overlaps:["gray", [int 4]; "ix", [int 2]]  
  [ctx; nbMulti; cFor "y"];  
!! simpl_mins [ctx];  
!! Matrix.storage_folding -dim:0 -size:(int 4) [ctx; multi cVarDef ["gray"; "ix"; "iy"]];  
!! Matrix.elim [ctx; multi cVarDef ["ixx"; "ixy"; "iyy"]];  
let inline v = Matrix.inline_constant -simpl -decl:[cVarDef v] [ctx; nbMulti; cArrayRead v] in  
!! List.iter inline ["weights_sobelX"; "weights_sobelY"; "weights_sum3x3"];  
let bind_gradient name =  
  Variable.bind_syntactic -dest:[ctx; tBefore; cVarDef "acc_sxx"] -fresh_name:(name ^ "${occ}") [ctx;  
    cArrayRead name] in  
!! List.iter bind_gradient ["ix"; "iy"];  
!! Matrix.elim_mops [ctx];  
!! Omp.parallel_for [ctx; cFor "y"];  
!! Omp.simd -clause:[Simdlen 8] [ctx; nbMulti; cFor "x"];
```

Expression Hoisting Transformation

`Loop.hoist_expr` is defined by combining simpler transformations.

```
let%transfo hoist_expr (* ... *) (tg : target) : unit =  
  (* .. calls hoist_expr_loop_list .. *)  
let%transfo hoist_expr_loop_list (* ... *) (tg : target) : unit =  
  Target.iter (fun t p ->  
    let instr_path = find_surrounding_instr p t in  
    Variable.bind name (target_of_path p);  
    hoist_decl_loop_list loops (target_of_path instr_path)) tg  
  
let%transfo hoist_decl_loop_list (* ... *) (tg : target) : unit =  
  (* .. calls hoist_alloc_loop_list .. *)  
  (* .. calls hoist_instr_loop_list .. *)  
  
let%transfo hoist_alloc_loop_list (* ... *) (tg : target) : unit =  
  (* .. calls Variable.init_detach, Matrix.intro_malloco, Instr.move,  
    Loop.move_out, Loop.hoist .. *)  
  
let%transfo hoist_instr_loop_list (* ... *) (tg : target) : unit =  
  (* .. calls Instr.move, Loop.move_out, Loop.fission .. *)
```
